

THE QUASI-PLANE MODEL FOR CALCULATING THE FRICTION DRAG ON A SHIP'S HULL

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Abstract: The paper presents the contributions of the authors regarding the extension of boundary layer theory for a plane plate to a quasi-cylindrical surface. Then the new model is applied to a ship's hull in order to determine the friction drag.

Keywords: boundary layer, quasi-plane, friction drag.

1. PRELIMINARY CONSIDERATIONS

Be T the draft ship full loaded. By cutting-off the hull with " m " equally spaced horizontal planes " Π_j ", with the levels, $z_j = j \frac{T}{m}$, $j = 1, 2, \dots, m$ we obtain the volumes V_j in Figure 1:

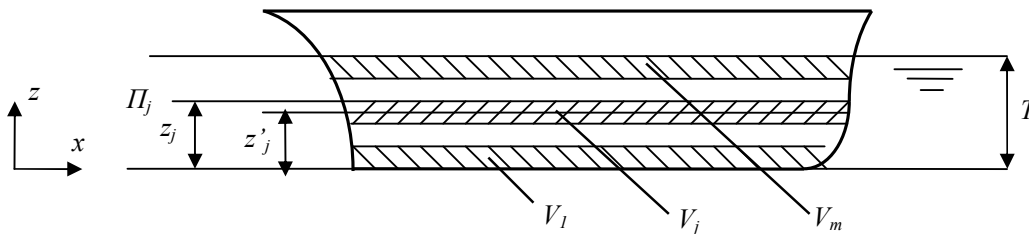


Figure 1

By cutting-off the volumes V_j with horizontal planes taken to the levels

$$z'_j = \frac{1}{2} \left[(j-1) \frac{T}{m} + j \frac{T}{m} \right] = (2j-1) \frac{T}{2m}, \quad j = 1, 2, \dots, m$$

, we obtain the water lines in Figure 2.

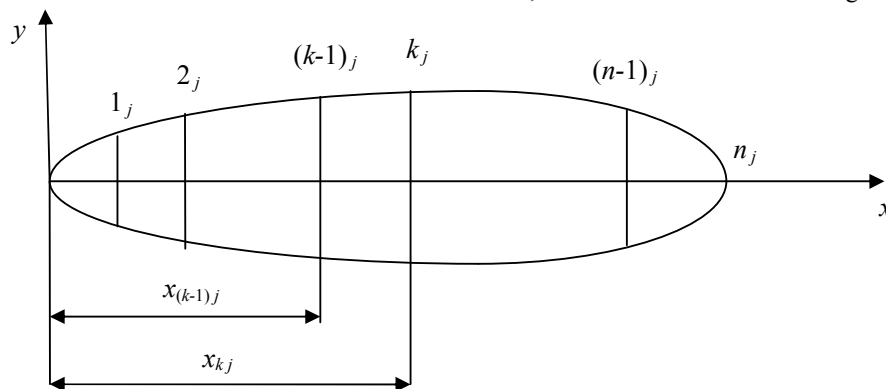


Figure 2

If the ratio $\frac{T}{m}$ is sufficiently small, then the bottom of the segments V_j are quasi-cylindrical, and the fluid flow around them is almost flat. Outlines the current line of L_j we choose the $1, 2, \dots, (n-1)_j, n_j$. In the proximity of the arc of the curve $(k-1)_j - k_j$ the velocity of current potential is equal to the weighted average velocity of the fluid $(k-1)_j$, and k_j , calculated by a procedure of Kármán type. The arch of the curve $(k-1)_j - k_j$ is then approximated through the string $(k-1)_j - k_j$.

If $v_{(k-1)_j}$ and v_{k_j} are the velocities in points $(k-1)_j$ and k_j , and $1, p_{kj}$ – is their weight, then the average weighted mead of fluid will be:

$$\bar{v}_{p_{kj}} = \frac{v_{(k-1)_j} + p_{kj} v_{k_j}}{1 + p_{kj}} \quad (1)$$

where $v_{(k-1)_j}$ and v_{k_j} is considered to be included in water line plane L_j .

As the weight p_{kj} , it is determined from the condition that $\bar{v}_{p_{kj}}$ to have a direction and purpose-oriented segment $(k-1)_j - k_j$ (see Figure 3).

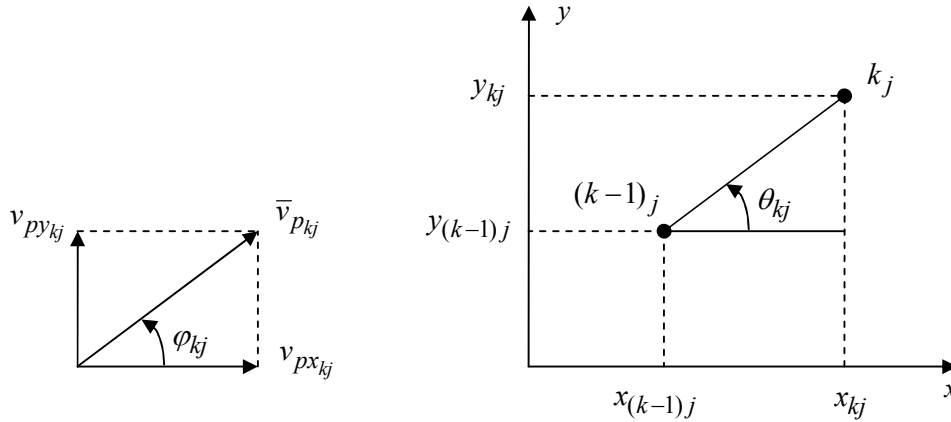


Figure 3

The above condition is equal to :

$$\tan(\varphi_{kj}) = \tan(\theta_{kj}) \quad (2)$$

yields:

$$\frac{v_{yp_{kj}}}{v_{xp_{kj}}} = \frac{y_{k_j} - y_{(k-1)_j}}{x_{k_j} - x_{(k-1)_j}} = m_{kj} \quad (3)$$

m_{kj} is noted as slope the segment defined by the points $(k-1)_j$ and k_j (string).

From the relation (1) we deduce that :

$$v_{yp_{kj}} = \frac{v_{y(k-1)_j} + p_{kj} v_{y_{k_j}}}{1 + p_{kj}} \quad \text{and} \quad v_{xp_{kj}} = \frac{v_{x(k-1)_j} + p_{kj} v_{x_{k_j}}}{1 + p_{kj}} \quad (4)$$

Thus, relation (1) becomes an equation with the independent variable „ p_{kj} ”:

$$\frac{v_{y(k-1)_j} + p_{kj} v_{y_{k_j}}}{v_{x(k-1)_j} + p_{kj} v_{x_{k_j}}} = m_{kj} \quad (5)$$

the solution

$$p_{kj} = \frac{-v_{y(k-1)j} + m_{kj}v_{x(k-1)j}}{v_{ykj} - m_{kj}v_{xkj}} \quad (6)$$

by having the weight p_{kj} , the relationship (1) is used to calculate the velocity v_{pkj} and its module:

$$\left| v_{pkj} \right| = v_{pkj} = \sqrt{\frac{(v_{x(k-1)j} + p_{kj}v_{xkj})^2 + (v_{y(k-1)j} + p_{kj}v_{ykj})^2}{(1 + p_{kj})^2}} \quad (7)$$

Remarks:

A numerical calculation carried out in accordance with the relationship (6) can lead to the following critical situations:

- (a) $m_{kj} = \frac{v_{ykj}}{v_{xkj}} \neq \frac{v_{y(k-1)j}}{v_{x(k-1)j}}$ (the denominator= 0)
- (b) $m_{kj} = \frac{v_{ykj}}{v_{xkj}} = \frac{v_{y(k-1)j}}{v_{x(k-1)j}} \quad \left(\frac{0}{0} \right)$
- (c) $p_{kj} = -1$ (denominator=0 in the formulae (7))

In the situation (a) the weight p_{kj} becomes infinite, and the relation (7) equals:

$$\begin{aligned} v_{pkj} &= \sqrt{\lim_{p_{kj} \rightarrow +\infty} \frac{(v_{x(k-1)j} + p_{kj}v_{xkj})^2 + (v_{y(k-1)j} + p_{kj}v_{ykj})^2}{(1 + p_{kj})^2}} = \\ &= \sqrt{v_{xkj}^2 + v_{ykj}^2} \end{aligned} \quad (8)$$

In situation (b) the relationship (6) presents an indetermination, type $\left(\frac{0}{0} \right)$, which amounts by applying the rule of l'Hôspital in relation to the variable m_{kj} :

$$p_{kj} = -\frac{v_{x(k-1)j}}{v_{xkj}} \quad (9)$$

If the above value is different from "-1", the relationship (7) obviously leads to a finite amount of it.

If, however, p_{kj} from the relation (9) has the "-1" value, it will be taken into account the fact that v_{pkj} velocity must be

finite, so the relationship (7) will present an indetermination type $\left(\frac{0}{0} \right)$ compared to the variable p_{kj} . Applying the rule of the l'Hôspital, it is successively obtained:

$$\begin{aligned} v_{pkj} &= \sqrt{\lim_{p_{kj} \rightarrow -1} \frac{(v_{x(k-1)j} + p_{kj}v_{xkj})^2 + (v_{y(k-1)j} + p_{kj}v_{ykj})^2}{(1 + p_{kj})^2}} = \\ &= \sqrt{\lim_{p_{kj} \rightarrow -1} \frac{(v_{x(k-1)j} + p_{kj}v_{xkj})v_{xkj} + (v_{y(k-1)j} + p_{kj}v_{ykj})v_{ykj}}{(1 + p_{kj})^2}} = \\ &= \sqrt{v_{xkj}^2 + v_{ykj}^2} \end{aligned} \quad (10)$$

the same as in the relation (8).

Therefore, we can determine the velocity v_{pkj} ($k=1,2,\dots,n$) in all situations.

Furthermore, the problem is reduced to the calculation of the tangential effort of friction developed on a plate plan by a current which is parallel to it, and having in the immediate vicinity of the boundary layer the velocity v_{pkj} .

2. THE CALCULATION OF THE TANGENTIAL EFFORT OF FRICTION AND OF THE FRICTION DRAG ON A SHIP

We consider the turbulent boundary layer created on a flat plate by a stream of fluid parallel to the plate, with the velocity v_0 . Kármán's integral equation associated with the exponent law $1/n$ of the velocity distribution, within the boundary layer is reduced to a simple differential equation of the form [2]:

$$\rho v_0^2 \frac{d\delta}{dx} \cdot \frac{n}{(n+1)(n+2)} = \tau_0 \quad (11)$$

where:

ρ - fluid density;

x - the direction of current fluid flow;

δ - the thickness of the boundary layer corresponding to an abscise (x);

τ_0 - Tangential friction effort on plate item built on the abscise " x ";

n - a natural number $n \in \{7, 9, 10\}$, dependent on the degree of turbulence of the flow.

As regarding the effort of friction τ_0 , it is determined by the relationship (2):

$$\tau_0 = 0,028 \left(\frac{n}{n+1} \right)^{1,75} \left(\frac{v}{v_0 \delta} \right)^{0,25} \rho v_0^2 \quad (12)$$

where v is their kinematics viscosity of the fluid.

Substituting τ_0 in the above differential equation (11) and then integrating it, it is obtained:

$$\delta^{1,25} = 0,028(n+2) \left(\frac{n}{n+1} \right)^{0,75} \left(\frac{v}{v_0} \right) x + C \quad (13)$$

The constant integration C is determined in the condition:

- for $x=0$, $\delta=\delta_0$ and so

$$\delta_0^{1,25} = 0,028(n+2) \left(\frac{n}{n+1} \right)^{0,75} \left(\frac{v}{v_0} \right)^{0,25} + \delta_0^{1,25} \quad (14)$$

Hence:

$$\delta^{0,25} = \left(\delta^{1,25} \right)^{0,2} = \left[0,028(n+2) \left(\frac{n}{n+1} \right)^{0,75} \left(\frac{v}{v_0} \right)^{0,25} + \delta_0^{1,25} \right]^{0,2} \quad (15)$$

The effort tangential of friction τ_0 becomes:

$$\tau_0 = \frac{0,028 \left(\frac{n}{n+1} \right)^{1,75} \left(\frac{v}{v_0} \right)^{0,25} \rho v_0^2}{\left[0,028(n+2) \left(\frac{n}{n+1} \right)^{0,75} \left(\frac{v}{v_0} \right)^{0,25} x + \delta_0^{1,25} \right]^{0,2}} \quad (16)$$

In the following we will expose the arguments that allow the extension of the validity of the relation (16) in the case of the boundary layer on a surface curve (the surface of the nautical careen):

- as resulting from chapter1 the surface of the careen was replaced by a union of flat panels with the height $\frac{T}{m}$ and length (measured in horizontal plane) equal to the length of strings $(k-1)_j - k_j$ (Figure 2);

- along such a panel the thickness of the boundary layer is measured in the plane of the water line L_j , in a normal direction on the string $(k-1)_j - k_j$ (obviously, if the water line L_j is located in the area of high plating, then the normal line is rigorously included in the plan line L_j);

- the direction „x” in the relationship (16) equals, in the case of the studied panel, (x_*) the segment-oriented direction $(k-1)_j - k_j$;

- the velocity v_0 becomes v_{pkj} ;

- $\delta = \delta_{(k-1)j}$; $\delta_{0j} = 0, (\forall j = 1, 2, \dots, m)$

Substituting the tangential effort of friction τ_0 with the symbol „ τ_{kj} ”, the relationship (16) becomes:

$$\tau_{kj} = \frac{0,028 \left(\frac{n}{n+1} \right)^{1,75} \left(\frac{v}{v_{pkj}} \right)^{0,25} \rho v_{pkj}^2}{\left[0,028(n+2) \left(\frac{n}{n+1} \right)^{0,75} \left(\frac{v}{v_{pkj}} \right)^{0,25} x_x + \delta_{(k-1)j}^{1,25} \right]^{0,2}} = \frac{\alpha_{kj}}{(a_{kj}x_x + b_{kj})^{0,2}} \quad (17)$$

(the correct α_{kj} , a_{kj} , b_{kj} is obvious).

Norming l_{kj} the length of the string $(k-1)_j - k_j$, the average amount of the tangential effort of friction $\bar{\tau}_{kj}$, becomes:

$$\begin{aligned} \bar{\tau}_{kj} &= \frac{1}{l_{kj}} \int_0^{l_{kj}} \frac{\alpha_{kj}}{(a_{kj}x_x + b_{kj})^{0,2}} dx_x = \frac{\alpha_{kj}}{l_{kj}a_{kj}} \int_{b_{kj}}^{a_{kj}l_{kj} + b_{kj}} \frac{du}{u^{0,2}} \\ &= 1,25 \frac{\alpha_{kj}}{l_{kj}a_{kj}} \left[(a_{kj}l_{kj} + b_{kj})^{0,8} - l_{kj}^{0,8} \right] \end{aligned} \quad (18)$$

The force of friction on the studied panel is :

$$F_{f_{kj}} = \bar{\tau}_{kj} A_{kj} \quad (19)$$

The projection of the force in the transverse of the ship will represent the friction drag developed by the panel „ k_j ”:

$$\begin{aligned} R_{f_{kj}} &= F_{f_{kj}} \cos \theta_{kj} \\ \cos \theta_{kj} &= \frac{x_{kj}}{l_{kj}} \end{aligned} \quad (20)$$

(see fig. 2, 3).

If we sum the friction drag both from the port and starboard side panel which are adjacent to the water line L_j , then we obtain :

$$R_{f_j} = 2 \sum_{k=1}^n R_{f_{kj}} \quad (21)$$

By adding the relationship (21) compared to „j”, it results the for calculus equation of the friction drag with the Appendix:

$$R_f = \sum_{j=1}^m R_{f_j} \quad (22)$$

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